Shape Feature Based Automatic Abnormality Detection of Cervico-Vaginal Pap Smears

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Abstract—Early detection of cervical cancer involves visual screening for changes in cellular morphology through microscopic analysis of Pap smears. Cytological interpretation by conventional microscopy of abnormal Pap smears performed manually is time-consuming, observer dependent and error prone. The aim of this study is to discriminate abnormal squamous cells from normal ones by quantitative image analysis of cervico-vaginal single cells with specific focus on the structure of the nuclei. In this study: 1) Six discriminative features such as nuclear area, nuclear perimeter, equivalent diameter, major axis length, minor axis length and convex area were selected and statistically justified, 2) A new dataset of 100 Pap smear cell images were collected from North-East Indian Regional population for the experimentation, and 3) Ground truth images of Pap smear cell dataset created by medical experts were compared with the automatically-segmented images with respect to the selected shape features. The cell boundary was segmented using greedy active contour model. Based on these six discriminating features, relevant cell images were classified as normal and abnormal using Support Vector Machine. Our method reports accuracy of 97.33%. Additionally, the proposed framework was applied to a known Pap smear benchmark dataset, to which we report an accuracy of 90.21%.

Index Terms—cervical cancer, cell imaging, pap smear test, nucleus, segmentation, greedy active contour model, feature extraction, support vector machine

I. INTRODUCTION

Cytology interpretation is an efficient and well-established technique for analysis and diagnosis of many diseases. It is considered as an essential method of early detection of dysplasia or precancerous cells. Cervical cancer is one of the most common cancer problems among women in the world [1]. In developing countries, it is the most common cause of cancer-related deaths in women [2]. There are various risk factors; however cervical cancer is mainly caused by Human Papillomavirus (HPV) types 16 and 18. Early detection and immediate follow-up treatment are considered as strong control measures against this cancer. Routine screening such as through a Pap smear test using Pap smear images is the most effective procedure for examining the precancerous cervix [3]-[5]. Dysplastic cells show precancerous changes; however, the visual interpretation of microscopic images are time-consuming, annoying and sometimes an error-prone process [5], [6]. Furthermore, due to different staining procedures, there exist variances in dye concentration and illumination of the cells and additional disturbances such as air drying, mucus or bacterial presence which make the recognition and interpretation process a more difficult task [7], [6]. In visual analysis of cells in Pap smears, the correct characterization of microscopic slides and drawing any conclusion depend mostly on the characteristic appearance of the nucleus in the cells. From pathological point of view, the nucleus of the infected cell may be excessively enlarged, or display irregularity in shape, with possibility of increased DNA content and irregular chromatin density [4]. The identification and estimation of these significant changes in the nucleus contribute, in part, to the discrimination of normal and abnormal cells in the microscopic images [8]. Therefore, it is essential to have an accurate determination of the nucleus area, nucleus shape and other nuclear characteristics of cells in cell images obtained by microscopy for accurate analysis. The major challenges for the detection of normal and abnormal cells are the exact detection of the location of cell nuclei automatically and accurate determination of the nuclear boundaries. Reliable cell nucleus segmentation methods are necessary, and many reports have used segmentation methods [9]-[12]. However, incorporation of nuclear structural features including accurate boundary determination has the potential to further improve the discrimination. Therefore, in this study several shape features for the nucleus were considered. The present study focuses on the quantitative analysis of the structure of cell nuclei from Pap smears in order to differentiate between normal and abnormal (premalignant/ malignant) squamous cells. The contributions of this article comprise i) creation of a new dataset of 100 numbers of Pap smear cell images of North-East Indian regional population, ii) creation of ground truth images of Pap smear cell dataset by medical experts, iii) comparison with the automatically segmented images with respect to their shape features, and iv) identification of abnormality present in the cervico-vaginal microscopic images. Initially, Pap smear images were enhanced and the boundary of the cell nuclei...
subsequently detected by greedy active contour model. The abnormality of the microscopic images was detected by observing the nucleus part of the cell. For this, eleven different shape features were considered for extraction from both normal and abnormal Pap smear cell images. Based on the t-test for adjudicating statistical significance on these eleven features only six of them could qualify the test and accordingly exploited for classification task. Classification of these cell images based on discriminant features was done using support vector machine (SVM) classifier. Experimentation and analysis are further conducted on a benchmark database to validate the classifier. 

Classification of cervico-vaginal cells from Pap smear images on the basis of histology and cytology have used several approaches according to reported research studies [9]. In order to detect the abnormality of microscopic cell images, the primary task is the detection of concerned cell nuclei, which reflects significant changes when the cell is cancerous. The localization of cell nuclei and the detection of the boundary of the cell nuclei are one set of the challenging tasks. Bamford et al. [9] suggested a useful method for nucleus boundary detection. They implemented Viterbi search-based dual active contour model to detect the nucleus boundary where the search space is bounded by the initial positions of inner/outer contours within/outside of the nucleus, and obtained a remarkable 99% success rate on a dataset including 20130 pap stained cell images [9]. Median filter has been found effective for reducing noise in Pap smear cell images [13], [8]. The Hough transformation [10] and morphological reconstruction process [11], [14] were also used successfully to detect the cell nuclei. The Fuzzy c-means clustering algorithm [15], [12], [14] was used effectively to split the segmented images in terms of abnormality and normality. Classification using support vector machine [17] and K-means clustering [8], [16], [13] yielded impressive results. 

Deformable model or GVF [15], [10], Active contour model [16], watershed transform algorithm [15], [16] have also been proved as effective ways of nucleus boundary detection. Yung-Fu Chen et al. [17] utilized semiautomatic cellular image analysis to segment nucleus and cytoplasm by Normalized Cross Correlation (NCC) detector and extracted different texture features to discriminate dysplastic cells from normal ones. Agarwal et al. used De-correlation stretching to enhance the discrimination between nucleus and background [18]. Cell nucleus segmented by Mean-shift based approach and adaptive image thresholding were also performed on the resultant image to convert into a binary image [18]. The Norup benchmark database [19] was used for validation.

### III. PROPOSED FRAMEWORK

Appropriate choice of shape based features useful for ascertaining the presence of abnormality in Pap smear images is absolutely important. An adequate and more appropriate feature set if used may provide improved classification accuracy. The framework of this study to classify a Pap-smear cytology image as depicted in Fig. 1.

![Figure 1. Framework of the proposed technique.](image)

#### A. Pre-Processing

For abnormality detection of cervico-vaginal microscopic images, the boundary between nucleus and cytoplasm in the cell are required to be clearly defined. The microscopic images are usually poor quality color images which are stained to color the cells and are affected by noise. To ensure homogeneity in the image content for subsequent processing, such cervico-vaginal Pap smear color images are converted into corresponding grey representation followed by contrast enhancement.

#### B. Region of Interest (ROI) Segmentation

As the size and shape of the nucleus indicate the presence of abnormality, identification of changes in the nucleus contributes to the discrimination of normal and abnormal cells in microscopic images. Dysplastic cells (abnormal cells) generally have longer or stretched nucleus and often oddly shaped whereas normal cells have a comparatively smaller and round/oval nucleus [8].

Objects having closed boundary in an image are usually subjected to different edge detection algorithms for isolation of their boundaries. In the present scope, we are inclined to use greedy active contour model instead, for identifying object contour present in the image. This is because greedy active contour model is adaptive to extraction of wide range of objects with complex and irregular shape as well as contour with broken boundaries [8]. For the sake of self-sufficiency, we illustrate the active contour model in brief. First, the user needs to specify contour points outside the region of interest and then the initialized points are involved in an iterative method for searching the local neighborhood around them to identify a set of new contour points having lower energy [20]. By moving towards lowest energy position, it extracts the desired object. The traditional snake is represented by a vector \( \mathbf{v}(s) \) as in (1) [20].

\[
\mathbf{v}(s) = (x(s), y(s))
\] (1)
In (1), \( x(s) \) and \( y(s) \) are the snake points in x-coordinate and y-coordinate, respectively. The energy function is a combination of internal energy due to bending and stretching of contour and image energy. The energy function \( E \) is represented by (2) [20].

\[
E = \int \left[ (\alpha(s)E_{\text{cont}} + \beta(s)E_{\text{curve}} + \gamma(s)E_{\text{image}}) \right] ds
\]  (2)

In (2), the \( E_{\text{cont}} \) and \( E_{\text{curve}} \) are first and second-order continuity constraints with their weighted coefficients. The \( E_{\text{image}} \) measures image quantity, namely the edge strength or intensity. Weighted coefficients in (2) are considered as Elastic constant \( (\alpha) = 1 \), Curvature constant \( (\beta) = 1 \), Image energy constant \( (\gamma) = 1.2 \) as per William et al. [20].

C. Shape Based Feature Extraction and Selection

After segmentation of the cell nucleus as the ROI using greedy Active Contour Model (ACM), eleven shape features, are illustrated below, were considered because of their significant role in identifying the abnormality.

1) **Nucleus Area (NA)**

   The nucleus area was determined from the total number of pixels in the segmented region [5], [20]-[23].

2) **Nucleus Perimeter (NP)**

   The nucleus perimeter was calculated by counting the number of boundary points [5], [16], [20]-[23].

3) **Nucleus Roundness (NR)**

   The nucleus roundness was calculated as the ratio between the actual area of the nuclear and the length of the perimeter of the nucleus. Circle has the roundness value exactly 1. The roundness value signifies the deviation of the shape of a cell from the circular shape. The nuclear roundness sometimes called circularity has been calculated by using the formulas [16], [13], [22].

   \[
   \text{Roundness} = \frac{4\pi \text{area}}{\text{perimeter}^2}
   \]  (3)

4) **Equivalent Diameter (ED)**

   Equivalent diameter specifies the diameter of a circle with the same area as the region [16], [21].

   \[
   \text{Equivalent \_ diameter} = \sqrt{\frac{4\text{area}}{\pi}}
   \]  (4)

5) **Major Axis Length (MAJ)**

   To find major axis length, a pair of points on the boundary is found whose Euclidean distance from each other is larger than any other pair of points on the boundary line. The line used to connect these two points is called major axis length [20], [24].

6) **Minor Axis Length (MIN)**

   Minor Axis length is the axis perpendicular to the major axis length [20], [24].

7) **Elongation (EN)**

   The elongation was calculated through minor axis length divided by major axis length. Circle has the elongation value exactly 1. From the elongation value, assumptions are generally made regarding how much a cell deviated from the circle [20], [24].

\[
\text{Elongation} = \frac{\text{Minor \_ Axis \_ Length}}{\text{Major \_ Axis \_ Length}}
\]  (5)

8) **Eccentricity (ECC)**

   It defines to evaluate the deviation of the objects shape from a symmetric or regular circular shape. It allows for tracking how much an abnormal cell nucleus differs how much from a normal cell nucleus. The values of eccentricity vary between 0 to 1 [21].

   \[
   \text{Eccentricity} = \sqrt{1-\left(\frac{\text{Minor \_ Axis \_ Length}}{\text{Major \_ Axis \_ Length}}\right)^2}
   \]  (6)

9) **Convex Area (CA)**

   Convex area specifies the total number of pixels in the convex hull image [20].

10) **Solidity (SO)**

    Solidity describes the quantity of the common pixels in the convex hull and in the region [21].

   \[
   \text{Solidity} = \frac{\text{Area}}{\text{Convex \_ Area}}
   \]  (7)

11) **Extent (EX)**

    Extent defines the ratio of pixel in the region to pixels in the total bounding box [21].

   \[
   \text{Extent} = \frac{\text{Area}}{\text{Area \_ of \_ the \_ bounding \_ box}}
   \]  (8)

Among these eleven shape features, some features may contribute significantly in comparison to the others. Pap smear images were evaluated for all eleven shape features to identify which features contribute with significance with \( p < 0.001 \) [25], [26].

D. **Classification**

These shortlisted six features were fed to the support vector machine to classify cell images as normal or abnormal cells.

**IV. NEW DATABASE DESIGN AND DEVELOPMENT**

Performance of the proposed framework was evaluated on the created North-East Indian regional population dataset.

A. **Database Description**

Our database was created in the Pathology Departments of Agartala Government Medical College in North East India and composed of 100 conventional Pap-stained cervical cell images. The images were taken randomly from 20 patients (5 images from each patient) of North-East Indian region population and found befitting for image analysis, acquired through a digital camera (OLYMPUS SP 350) adapted to a light microscope (OLYMPUS CX41) having 80 megapixels resolutions and stored in JPEG format of 132 X 158 pixels. As illustrated in Table 1, among 20 patients, 10 patients had normal and 10 patients had abnormal cells based on the observation of the pathology expert at the hospital.
B. **Cell Staining**

Cells obtained from cervico-vaginal swabs were stained. Papanicolaou-type stains were used for identification of features related to nucleus [27]. Fig. 2 depicts the steps used for cell preparation.

Papanicolaou stain requires immediate and rapid fixation in alcohol to preserve the details of cells and to avoid the smears drying out. Ethanol (95%) was used [27] and haematoxylin stain, which is a natural dye which stains the nucleus part of a cell and Orange green 6 which stain the cytoplasm of keratinized cells, were used. Polychromic stain, a mixture of Light Green SF and Eosin G, were used as the cytoplasmic stain. Clearing in xylol produced cellular transparency prior to mounting. Mounting was performed with DPX which is a mixture of distyrene, a plasticizer, and xylene. Representative normal microscopic cell images and abnormal microscopic cell images are shown in Fig. 3.

<table>
<thead>
<tr>
<th>TABLE I. SAMPLES IN THE CREATED DATABASE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Category of Pap Smears</td>
</tr>
<tr>
<td>-------------------------</td>
</tr>
<tr>
<td>Normal</td>
</tr>
<tr>
<td>Abnormal</td>
</tr>
</tbody>
</table>

Figure 2. Stages of data preparation.

![Figure 2](image2.png)

**Figure 3.** Created dataset of Pap smear images. (a) and (b) indicate Normal Pap smear cell images, (c) and (d) indicate abnormal Pap smear cell images.

C. **Ground Truth Generation**

Ground truth generation is a crucial work to verify the competence of the proposed framework. Generally ground truths are generated using manual segmentation by the physicians and medical experts to visually identify the presence of abnormality. In the terms of medical image processing, these ground truths can also be used to measure the performance of different segmentation algorithms. Norup and another group Martin et al. consider CHAMP software to segment Pap smear images. Unfortunately, CHAMP software cannot provide a satisfying segmentation performance, especially for abnormal cells [8].

Three distinct set of ground truths for Pap smear cell database were generated by three independent medical experts individually using the widely used Sefexa image segmentation tool [28] while keeping all parameters same for the whole database. Sefexa makes the manual segmentation of nucleus region of Pap smears appear as depicted in Fig. 4(d).

V. **EXPERIMENTAL RESULTS AND DISCUSSION**

The objective of this section is to investigate the performance of the automated framework compared to ground truth. Fig. 4 illustrates subsequent phases of nuclear delineation using greedy active contour model and typical one among the three separate ground truths (due to space limitation) prepared manually by three individual medical experts.

![Figure 4](image4.png)

Figure 4. (a₁ – a₄) Normal and abnormal Pap smear cell images of created dataset, (b₁-b₄) represents initialization of ACM on input, (c₁– c₄) segmented image using ACM, (d₁–d₄) Ground truth image.

Comprehensive range of eleven shape features extracted from automated segmented nucleus was compared with the range of features extracted manually from the nucleus. The comparative results are shown in Table II, wherein a sharp discrimination was observed between normal and abnormal cell images only for the shortlisted six shape features.

Extraction of the shape features was followed by the evaluation of the statistical significance of theses shape features in abnormality detection, followed by SVM classification [29]. The average of these feature values along with their standard deviation are listed in Table III and statistical significance of these features are tested by using independent sample t-test [30], [31] with significance level of 0.1%. The shape features whose t-value is greater than the critical value or the p-value<0.001 are considered to be statistically significant and the features, whose t-value is less than the critical
value or p-value $>0.001$ are considered to be statistically insignificant in abnormality detection. As illustrated in Table III, out of 11 shape features, only 6 features: Nucleus Area, Nucleus Perimeter, Equivalent diameter, Major Axis Length, Minor Axis length and Convex area were found to be statistically significant ($p<0.001$) in discriminating abnormal cells from the normal ones.

**TABLE II. ELEVEN SHAPE FEATURES OBTAINED AUTOMATICALLY AND FEATURES FROM GROUND TRUTH IMAGE THEREOF**

<table>
<thead>
<tr>
<th>Shape Features</th>
<th>Range of Features Obtained Automatically From Segmented Image</th>
<th>Range of Features Obtained Automatically From Ground Truths</th>
</tr>
</thead>
<tbody>
<tr>
<td>Normal cell</td>
<td>Abnormal cell</td>
<td>Normal cell</td>
</tr>
<tr>
<td>NA (µm²)</td>
<td>99-1282</td>
<td>3052-6085</td>
</tr>
<tr>
<td>NP (µm)</td>
<td>54-166</td>
<td>212-496</td>
</tr>
<tr>
<td>NR</td>
<td>0.415-0.585</td>
<td>0.343-0.595</td>
</tr>
<tr>
<td>ED (µm)</td>
<td>11.227-40.402</td>
<td>50.802-120.784</td>
</tr>
<tr>
<td>MAJ (µm)</td>
<td>15.183-48.365</td>
<td>55.123-132.43</td>
</tr>
<tr>
<td>MIN (µm)</td>
<td>8.386-34.802</td>
<td>44.2-111.17</td>
</tr>
<tr>
<td>EN</td>
<td>0.525-0.934</td>
<td>0.360-0.977</td>
</tr>
<tr>
<td>ECC</td>
<td>0.357-0.852</td>
<td>0.215-0.933</td>
</tr>
<tr>
<td>SO</td>
<td>0.887-0.973</td>
<td>0.916-0.988</td>
</tr>
<tr>
<td>EX</td>
<td>0.605-0.819</td>
<td>0.449-0.783</td>
</tr>
<tr>
<td>CA (µm²)</td>
<td>105-1326</td>
<td>2112-11690</td>
</tr>
</tbody>
</table>

**TABLE III. MEAN AND STANDARD DEVIATION OF SHAPE FEATURES FROM CREATED DATASET WITH SIGNIFICANCE VALUE**

<table>
<thead>
<tr>
<th>Shape Features</th>
<th>Mean ± Standard Deviation</th>
<th>t value</th>
<th>p value</th>
</tr>
</thead>
<tbody>
<tr>
<td>NA (µm²)</td>
<td>456.94±250.10</td>
<td>4029.78±1410.06</td>
<td>864.523</td>
</tr>
<tr>
<td>NP (µm)</td>
<td>103.28±26.18</td>
<td>315.36±84.17</td>
<td>209.688</td>
</tr>
<tr>
<td>NR</td>
<td>0.50±0.037</td>
<td>0.52±0.047</td>
<td>1.926</td>
</tr>
<tr>
<td>ED (µm)</td>
<td>23.30±6.26</td>
<td>72.48±19.85</td>
<td>102.253</td>
</tr>
<tr>
<td>MAJ (µm)</td>
<td>27.46±7.81</td>
<td>85.98±25.40</td>
<td>106.733</td>
</tr>
<tr>
<td>MN</td>
<td>20.26±5.52</td>
<td>62.87±18.57</td>
<td>94.270</td>
</tr>
<tr>
<td>EN</td>
<td>0.74±0.11</td>
<td>0.74±0.14</td>
<td>0.466</td>
</tr>
<tr>
<td>ECC</td>
<td>0.64±0.13</td>
<td>0.62±0.16</td>
<td>0.466</td>
</tr>
<tr>
<td>SO</td>
<td>0.95±0.01</td>
<td>0.96±0.01</td>
<td>1.224</td>
</tr>
<tr>
<td>EX</td>
<td>0.70±0.04</td>
<td>0.70±0.06</td>
<td>0.766</td>
</tr>
<tr>
<td>CA (µm²)</td>
<td>478.04±258.03</td>
<td>4589.22±2294.19</td>
<td>892.571</td>
</tr>
</tbody>
</table>

For each data sample in the created dataset and benchmark dataset, the discriminative shape features were used as features for the support vector machine classifier. In this study the classification is treated as a two class pattern classification (Normal and Abnormal) problem. For training, support vector machine linear kernel was used. To obtain proper parameters for kernel function, 5-fold cross validation was performed for both the databases. Here, 70% of the data were selected randomly from both datasets for training and 30% were for testing. As a result, the accuracy of the method was 97.33%. Additionally, the proposed framework was applied to a known Pap smear benchmark dataset, and we determined an accuracy of 90.21%. There are only few reports in literature on this benchmark database that classify cell images as normal and abnormal. For example, Sa et al. reported 89.64% accuracy on the same Pap smear benchmark database for two-class (normal and abnormal) problem using gravitational method [32]. Mbaga et al. mentions a promising result with an average accuracy of 92.961% [33]. Paul et al. report impressive results of 92.37% and 98.31 % accuracy for minimum distance and K-nearest neighbor classifiers, respectively [34]. Sun et al. report accuracy up to 94.44% using random forest classifier [35].

**VI. CONCLUSION**

In this study a North-East Indian regional population dataset were developed with its corresponding ground truth images that were provided by medical experts. Out of the eleven shape features, six discriminative and statistically justified shape features were extracted to classify Pap smear cell images into normal and abnormal smears using support vector machine. The results of these studies reveal additionally that support vector machine gives an impressive performance with potential to provide higher accuracy.

ACKNOWLEDGMENT

The research work was supported by the Grant BT/553/NE/TBP/2013 from the Department of Biotechnology, Government of India to M. K. Bhowmik conducted at the Biometrics Laboratory of Computer Science and Engineering, NYIT.-ISRC-2016 and -ISRC-2017 to N. Nath supported histochemical analysis and software.

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